

# **GALLIUM-NITRIDE INVERTER FOR** ELECTRIC AIRCRAFT PROPULSION

### Amazon Prime Air – Electric Drone Delivery System

- Amazon Prime Air designs drones for delivery that operate using an electric propulsion system.
- Amazon would like to improve the efficiency and power density of these systems by using wide bandgap (WBG) devices in their motor drives, effectively increasing the drone's range.



### **GaN MOSFETs for Power Electronics Systems**

- Why GaN for motor drives?
- Faster switching frequency
- Higher power density
- No reverse recovery losses
- Higher efficiency low Rdson
- GaN devices have significantly lower on-resistance than their Si counterparts at the same operating voltage, making them a more efficient alternative.



• The power electronics of an electric propulsion system are currently the limiting factor in achieving higher voltages and efficiency. Therefore, improving inverter performance will yield the largest system benefits.

### **GaN Inverter Features**

• The team-designed inverter is intended to operate with a 70 V ESS and 2 kW electric motor.

### Motor Drive System Overview



### Features & Specifications:

- 100 V, 90 A GaN MOSFETs
- 200 kHz switching frequency for initial design
- 250 µF bulk capacitance to reduce ESS current ripple
- Top-side air-cooled MOSFET design
- Onboard auxiliary power conversion
- Onboard DSP microcontroller for open loop operation • Small footprint for high power density

# ELECTRICAL & COMPUTER ENGINEERING

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### **Inverter Modeling & Simulation**

- During the design process, the software PLECs was used to model the inverter, specify circuit components, and simulate performance metrics.
- The system was modeled and will be tested using an RL load instead of a PM motor for design and validation simplicity.



- The switching frequency  $(f_{sw})$  is an important design parameter in PMSM drives, as there are multiple design trade-offs to consider. Increasing the switching frequency generally leads to:
  - Higher inverter losses and worse EMI/EMC.
- Improved torque ripple, motor efficiency, and motor control. • The team's model only considers inverter efficiency and not the overall system as motors may change.
- Predicted average efficiency of the inverter @ 200 kHz  $f_{sw}$ : • 96.45 %
- Predicted peak efficiency of the inverter under full load @ 200 kHz  $f_{sw}$ : • 98.7 %

### **Circuit & Critical Loop Design Considerations**

- GaN devices are significantly more sensitive than their Silicon counterparts. • Minimizing parasitics and large voltage/current changes is extremely important to consider in
- design.
- Primarily, the critical loop between the half-bridge MOSFETs and their decoupling capacitors must be as tight as possible.



**GaN Systems** 61008T MOSFET [3]





• To minimize this loop, the FETs were placed closely together as shown. The decoupling caps are placed directly below the transistors on the bottom side of the board.

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**Bottom Side Caps** 

# **Inverter PCB Design**

- A 4-layer PCB prototype was developed for hardware tests to validate performance and efficiency metrics.
- The PCB includes a footprint to directly attach a TI C2000 LaunchPad microcontroller.



- Overall Board Dimensions: 8 in x 4 in
- The microcontroller consumes the majority of the board space. The power stage itself uses about 7 in<sup>2</sup>

- frequencies.
- Improved thermal management design.
- Open loop motor testing to validate full system performance.
- Iterative improvements on PCB layout based on test results & feedback.
- EMI/EMC studies of the system.

Air/b?ie=UTF8&node=8037720011> [Accessed 27 May 2020]. UsingEnhancementMode.aspx> [Accessed 27 May 2020]. transistors/gs61008t/> [Accessed 27 May 2020].

• Onboard current and voltage sensing for testing and future closed loop control.

### **Future Work & References**

- Performing hardware tests to compare efficiency against various switching
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